# Cardinal Interpolation and Spline Functions: II Interpolation of Data of Power Growth* ${ }^{*+}$ 

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#### Abstract

Let $m$ be a natural number and let $S_{m}$ denote the class of functions $S(x)$ of the following nature: If $m$ is even, then $S(x)$ is a polynomial of degree $m-1$ in each unit interval ( $\nu, \nu+1$ ) for all integer values of $\nu$, while $S(x) \in C^{m-2}$ on the entire real axis. If $m$ is odd, then the conditions are the same except that the intervals $(\nu, \nu+1)$ are replaced by $\left(\nu-\frac{1}{2}, \nu+\frac{1}{2}\right)$. The main result is as follows: If a sequence $\left(y_{\nu}\right)(-\infty<\nu<\infty)$ of numbers is preassigned such that $y_{v}=O\left(|\nu|^{*}\right)$ as $\nu \rightarrow \pm \infty$, with $s \geqslant 0$, then there exists a unique $S(x) \in S_{m}$ satisfying the relations $S(\nu)=y_{\nu}$, for all integer $\nu$, and the growth condition $S(x)=O\left(|x|^{s}\right)$ as $x \rightarrow \pm \infty$.


## Introduction and Statement of Results

Let $m$ be a natural number and let $S_{m}$ denote the class of spline functions of degree $m-1$, or order $m$, defined on the entire axis of reals and having simple knots at the integers $\nu$ if $m$ is even, or at the half-way points $\nu+\frac{1}{2}$ if $m$ is odd. This means that $S(x) \in S_{m}$ provided that $S(x) \in C^{m-2}$ (for $m=1$ this condition is vacuous) and that the restriction of $S(x)$ to any interval between consecutive knots is identical with a polynomial of degree not exceeding $m-1$. Such functions are called cardinal spline functions.

Let $y=\left(y_{v}\right)$ be a prescribed sequence of numbers, the subscript $\nu$ ranging over all integers. The problem of finding a function $F(x)(-\infty<x<\infty)$ satisfying the relations

$$
\begin{equation*}
F(\nu)=y_{v} \quad \text { for all } \quad \nu, \tag{1}
\end{equation*}
$$

[^0]and such that $F(x)$ belongs to some prescribed linear space $\mathscr{P}$ is called a cardinal interpolation problem and denoted by the symbol
\[

$$
\begin{equation*}
\operatorname{CIP}(y ; \mathscr{P}) \tag{2}
\end{equation*}
$$

\]

Before we proceed with the contents of this paper it is important for both motivation and orientation to state and prove the following

Lemma 1. Let $m \geqslant 2$ and let the sequence ( $y_{v}$ ) be arbitrarily assigned. The

$$
\begin{equation*}
\operatorname{CLP}\left(y ; S_{m}\right) \tag{3}
\end{equation*}
$$

always has solutions and all its solutions form a linear manifold of dimension $2[(m-1) / 2]$, i.e., its dimension is $m-2$ if $m$ is even and $m-1$ if $m$ is odd.

Proof. Let us construct a solution $S(x)$ of the problem (3).
Case $1 . m$ is even. The knots of $S(x)$ are at the integers. Choose $S(x)=P(x) \in \pi_{m-1}$ in $0 \leqslant x \leqslant 1$, the polynomial $P(x)$ being only required to satisfy the conditions

$$
\begin{equation*}
P(0)=y_{0} \quad \text { and } \quad P(1)=y_{1} \tag{4}
\end{equation*}
$$

The entire solution $S(x)$ may now be written in the form

$$
\begin{align*}
S(x)= & P(x)+a_{1}(x-1)_{+}^{m-1}+a_{2}(x-2)_{+}^{m-1} \\
& +\cdots+a_{0}(-x)_{+}^{m-1}+a_{-1}(-x-1)_{+}^{m-1}+\cdots, \tag{5}
\end{align*}
$$

where $u_{+}=u$ if $u \geqslant 0$ and $u_{+}=0$ if $u<0$. Observe that the interpolation conditions

$$
S(\nu)=y_{v} \quad \text { for } \quad v=2,3, \ldots
$$

determine successively and uniquely the coefficients $a_{1}, a_{2}, \ldots$, respectively, while the conditions

$$
S(\nu)=y_{v} \quad \text { for } \quad \nu=-1,-2, \ldots,
$$

likewise determine successively and uniquely the coefficients $a_{0}, a_{-1}, \ldots$, respectively. Thus, indeed, the solution $S(x)$ is uniquely defined by the choice of the polynomial $P(x)$. Since $P(x)$ depends on $m-2$ linear parameters, the proof for this case is complete.

Case 2. $m$ is odd. The knots are now at the points $v+\frac{1}{2}$. We choose $S(x)=Q(x) \in \pi_{m-1}$, in $-\frac{1}{2} \leqslant x \leqslant \frac{1}{2}$, requiring $Q(x)$ to satisfy

$$
\begin{equation*}
Q(0)=y_{0} . \tag{6}
\end{equation*}
$$

After this choice the solution of (3) is uniquely defined by

$$
\begin{aligned}
S(x)= & Q(x)+b_{1}\left(x-\frac{1}{2}\right)_{+}^{m-1}+b_{2}\left(x-\frac{3}{2}\right)_{+}^{m-1} \\
& +\cdots+b_{0}\left(-x-\frac{1}{2}\right)_{+}^{m-1}+b_{-1}\left(-x-\frac{3}{2}\right)_{+}^{m-1}+\cdots,
\end{aligned}
$$

where the coefficients are uniquely and successively determined from $S(\nu)=y_{v}(\nu \neq 0)$ as before. As $Q(x)$, subject to (6), depends on $m-1$ linear parameters, the proof of Lemma 1 is complete.

If $m=2$, which is the case of linear spline functions, the problem (3) has a unique solution.

If $m \geqslant 3$, then most of the solutions of (3) are perfectly wild and useless functions. It is clear that some further useful restrictions on $\left(y_{v}\right)$ and on the interpolant $S(x)$ are needed. Two such restrictions were given in [4] by prescribing the following two choices for the space $\mathscr{S}$ :

$$
\begin{equation*}
\mathscr{S}_{1}=S_{m+1} \cap L_{p}{ }^{m} \quad \text { and } \quad \mathscr{S}_{2}=S_{2 m} \cap L_{2}^{m} . \tag{7}
\end{equation*}
$$

Here $1 \leqslant p \leqslant \infty$ and $L_{p}{ }^{m}$ is the class of functions $F(x)$ such that $F^{(m)}(x) \in L_{p}$. It was shown that both these problems have solutions, and then unique solutions, if and only if the sequence ( $y_{v}$ ) satisfies the condition

$$
\begin{equation*}
\Delta^{m} y=\left(\Delta^{m} y_{v}\right) \in l_{p} \tag{8}
\end{equation*}
$$

The present paper is a supplement to [4]. We discuss first the problem (2) for more general and perhaps also more useful spaces $\mathscr{P}$, namely, the following: Let $s \geqslant 0$ and let us consider the class

$$
\begin{equation*}
F_{s}=\left\{F(x) ; F(x) \in C, \quad F(x)=O\left(|x|^{s}\right) \quad \text { as } \quad x \rightarrow \pm \infty\right\} \tag{9}
\end{equation*}
$$

In particular, $F_{0}$ is the class of bounded and continuous functions. We may also describe the class

$$
\begin{equation*}
F^{*}=\bigcup_{s \geqslant 0} F_{s} \tag{10}
\end{equation*}
$$

as the class of functions of power growth.
Correspondingly, let

$$
\begin{equation*}
Y_{s}=\left\{y=\left(y_{v}\right) ; \quad y_{\nu}=O\left(|\nu|^{8}\right) \quad \text { as } \quad \nu \rightarrow \pm \infty\right\} \tag{11}
\end{equation*}
$$

and

$$
\begin{equation*}
Y^{*}=\bigcup_{s \geqslant 0} Y_{s} . \tag{12}
\end{equation*}
$$

Our present main results on cardinal spline interpolation are the following theorems.

Theorem 1. The

$$
\begin{equation*}
\operatorname{CIP}\left(y ; S_{m} \cap F_{s}\right) \tag{13}
\end{equation*}
$$

has solutions if and only if

$$
\begin{equation*}
y \in Y_{s} \tag{14}
\end{equation*}
$$

and then the problem (13) has a unique solution.
This theorem shows that the interpolation conditions (1) set up a one-to-one correspondence between the elements of the two classes

$$
S_{m} \cap F^{*} \quad \text { and } \quad Y^{*}
$$

Let us now consider the unit-sequence

$$
\delta=\left(\delta_{\nu}\right), \quad \text { where } \quad \delta_{\nu}= \begin{cases}1 & \text { if } \quad \nu=0  \tag{15}\\ 0 & \text { if } \quad \nu \neq 0\end{cases}
$$

Evidently $\delta \in Y_{0}$ and by Theorem 1 the $\operatorname{CIP}\left(\delta ; S_{m} \cap F_{0}\right.$ ) has a unique solution that we denote by $L_{m}(x)$. Thus

$$
\begin{equation*}
L_{m}(\nu)=\delta_{v} \quad \text { for all } \quad \nu \tag{16}
\end{equation*}
$$

Theorem 2. The function $L_{m}(x)$ satisfies an inequality of the form

$$
\begin{equation*}
\left|L_{m}(x)\right|<C_{m} \exp \left(-\gamma_{m}|x|\right) \quad \text { for all real } x \tag{17}
\end{equation*}
$$

where $C_{m}$ and $\gamma_{m}$ are positive constants.

Theorem 3. If the condition (14) is satisfied, then the unique solution $S(x)$ of the problem (13) is given by "Lagrange's formula"

$$
\begin{equation*}
S(x)=\sum_{-\infty}^{\infty} y_{v} L_{m}(x-v) \tag{18}
\end{equation*}
$$

which converges locally uniformly.
We note the
Corollary 1. If $S(x) \in S_{m} \cap F^{*}$ then the relation

$$
\begin{equation*}
S(x)=\sum_{-\infty}^{\infty} S(\nu) L_{m}(x-\nu) \tag{19}
\end{equation*}
$$

is an identity.

Because of its role in Theorem 3 we call $L_{m}(x)$ the fundamental cardinal spline function of order $m$, or degree $m-1$.

All these theorems are evident if $m=1$, or $m=2$. In particular, $L_{2}(x)$ is the well-known "roof-function"

$$
L_{2}(x)=\left\{\begin{array}{l}
1+x \quad \text { in }[-1,0] \\
1-x \quad \text { in }[0,1] \\
0 \quad \text { elsewhere }
\end{array}\right.
$$

and the formula (18) gives the unique interpolant in $S_{2}$ for perfectly arbitrary data $\left(y_{v}\right)$. The theorems are no longer evident if $m \geqslant 3$. For instance, it is by no means trivial that if $\left(y_{v}\right)$ is a bounded sequence then there is a unique interpolating function $S(x)$ satisfying

$$
S(x) \in C^{1}, \quad S(x) \in F^{*}
$$

and that reduces to a quadratic function on each interval ( $\nu-\frac{1}{2}, \nu+\frac{1}{2}$ ) for all integers $\nu$. Moreover, this unique $S(x)$ is bounded.

For the origin of the term "cardinal" in the present context, see [3, pp. 4647].

Before we mention the second subject of this paper, we recall the following known facts. Let

$$
M_{1}(x)= \begin{cases}1 & \text { if }-\frac{1}{2} \leqslant x \leqslant \frac{1}{2}  \tag{20}\\ 10 & \text { elsewhere }\end{cases}
$$

and let

$$
\begin{equation*}
M_{m}(x)=\overbrace{M_{1} * \cdots * M_{1}(x)}^{m} \tag{21}
\end{equation*}
$$

be the result of convoluting $M_{1}(x)$ with itself $m$ times. It is easily seen that

$$
\begin{equation*}
M_{m}(x) \in S_{r n} \tag{22}
\end{equation*}
$$

and that the support of $M_{m}(x)$ is contained in (一 $\frac{1}{2} m, \frac{1}{2} m$ ). The spline function $M_{m}(x)$ is called a basis-spline, or $B$-spline, because of the following property [3, Part A, Section 3.15, Theorem 5]. If

$$
\begin{equation*}
S(x) \in S_{m}, \tag{23}
\end{equation*}
$$

then $S(x)$ admits a unique representation of the form

$$
\begin{equation*}
S(x)=\sum_{-\infty}^{\infty} c_{\nu} M_{m}(x-\nu) \tag{24}
\end{equation*}
$$

and, conversely, any such series with arbitrarily prescribed $\left(c_{\nu}\right)$ converges and (23) holds.

Notice that $M_{m}(x)=L_{m}(x)$ if $m=1$ or $m=2$, but this is no longer true if $m \geqslant 3$.

Let (23) and (24) hold. When is $S(x) \in L_{p}$ ? An answer is provided by Theorem 12 of [4] which we restate here as

Theorem 4. Let (23) and (24) hold and let $1 \leqslant p \leqslant \infty$. Then

$$
\begin{equation*}
S(x) \in L_{p} \tag{25}
\end{equation*}
$$

if and only if

$$
\begin{equation*}
\left(c_{v}\right) \in l_{p} \tag{26}
\end{equation*}
$$

We give here a new proof of Theorem 4. It will rather easily follow from the following result that is perhaps of independent interest.

ThEOREM 5. Let $\left(\gamma_{2 r}^{(m)}\right)$ be the sequence of rational numbers generated by the expansion

$$
\begin{equation*}
\left(\frac{u}{2 \sin (u / 2)}\right)^{m}=\sum_{r=0}^{\infty} \gamma_{2 r}^{(m)} u^{2 r} \tag{27}
\end{equation*}
$$

If (23) and (24) hold, then the coefficients $c_{\nu}$ in (24) may be expressed as

$$
\begin{equation*}
c_{v}=\sum_{r=0}^{s}(-1)^{r} \gamma_{2 r}^{(m)} S^{(2 r)}(\nu), \quad \text { where } \quad s=[(m-1) / 2] \tag{28}
\end{equation*}
$$

This may be regarded as an analogue for cardinal spline functions of Taylor's formula for polynomials.

From (27) we find that

$$
\gamma_{2}^{(m)}=m / 24, \quad \gamma_{4}^{(m)}=m(5 m+2) / 5760
$$

whence (28) assumes the following explicit forms:

$$
\begin{array}{ll}
m=2, & c_{\nu}=S(\nu) \\
m=3, & c_{\nu}=S(\nu)-(1 / 8) S^{\prime \prime}(\nu) \\
m=4, & c_{v}=S(\nu)-(1 / 6) S^{\prime \prime}(\nu) \\
m=5, & c_{v}=S(\nu)-(5 / 24) S^{\prime \prime}(\nu)+(3 / 128) S^{(4)}(\nu) \\
m=6, & c_{v}=S(\nu)-\frac{1}{4} S^{\prime \prime}(\nu)+(1 / 30) S^{(4)}(\nu)
\end{array}
$$

In Section 1 below we describe a few applications of Theorems 1 and 3. A characterization of periodic spline interpolants to periodic data follows very easily (Theorem 6). The most beautiful and most important spline functions and monosplines are the so-called Euler splines $\mathscr{E}_{m}(x)$ and the Bernoulli monosplines $\bar{B}_{m}(x)$. New characterizations of these functions are obtained (Theorems 7 and 8).

In Sections 2-7, Theorems 1-5 are established by using some results from [3, 4].

## 1. A Few Applications

A. The case of periodic sequences ( $y_{\nu}$ )

Let us apply Theorem 1 to the case when

$$
\begin{equation*}
\left(y_{v}\right) \text { is a periodic sequence of period } n . \tag{1.1}
\end{equation*}
$$

Since $\left(y_{v}\right) \in Y_{0}$ it follows that the $\operatorname{CIP}\left(y ; S_{m} \cap F_{0}\right)$ has a unique solution. Since $S(\nu)=y_{\nu}$ for all $\nu$, (1.1) implies that $S(\nu+n)=y_{\nu+n}=y_{\nu}$, or

$$
S(\nu+n)=y_{\nu}
$$

for all $\nu$. Therefore $S(x+n)$ is another solution of our problem. From the unicity we conclude that $S(x+n)=S(x)$. This establishes

Theorem 6. If $\left(y_{\nu}\right)$ is a periodic sequence of period $n$, then the unique solution of the

$$
\begin{equation*}
\operatorname{CIP}\left(y ; S_{m} \cap F^{*}\right) \tag{1.2}
\end{equation*}
$$

is periodic of period $n$.
The periodicity of $S(x)$ becomes immediately apparent if we use its Lagrange representation (18). In our case, (18) becomes

$$
\begin{equation*}
S(x)=\sum_{0}^{n-1} y_{v} l_{\nu}(x) \tag{1.3}
\end{equation*}
$$

where

$$
\begin{equation*}
l_{\nu}(x)=\sum_{j=-\infty}^{\infty} L_{m}(x-\nu-j n) \tag{1.4}
\end{equation*}
$$

are $n$ fixed periodic elements of $S_{m}$ that form a base for all such functions.

## B. The Euler splines

We consider the simplest nontrivial periodic sequence

$$
\begin{equation*}
y_{v}=(-1)^{v} \quad \text { for all } \nu \tag{1.5}
\end{equation*}
$$

By Theorem 6 we obtain
Theorem 7. The

$$
\begin{equation*}
\operatorname{CLP}\left((-1)^{\nu} ; S_{m+1} \cap F^{*}\right) \tag{1.6}
\end{equation*}
$$

has a unique solution denoted by $\mathscr{E}_{m}(x)$ and called the Euler spline of degree $m ; \mathscr{E}_{m}(x)$ is periodic of period 2.

This is a new characterization of the Euler spline $\mathscr{E}_{m}(x)$ within the class $S_{m+1}$. An entirely different characterization of $\mathscr{E}_{m}(x)$ was recently discussed by Cavaretta [1].

We have already mentioned the relations

$$
\begin{equation*}
\mathscr{E}_{m}(\nu)=(-1)^{\nu} \quad \text { for all } \quad \nu \tag{1.7}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathscr{E}_{m}(x+2)=\mathscr{E}_{m}(x) \tag{1.8}
\end{equation*}
$$

From (1.7) we get $-\mathscr{E}_{m}(\nu-1)=(-1)^{\nu}$ whence the unicity shows that

$$
\begin{equation*}
\mathscr{E}_{m}(x-1)=-\mathscr{E}_{m}(x) \tag{1.9}
\end{equation*}
$$

We could develop the further properties of $\mathscr{E}_{m}(x)$ from its present definition. However, for brevity we only remark the following: Nörlund [2, Section 2] discusses the properties of the Euler polynomials $E_{m}(x)$, defined as the solutions of the identity $E_{m}(x+1)+E_{m}(x)=2 x^{m}$, and forms the periodic function $\bar{E}_{m}(x)$ of period 2. From Nörlund's discussion it is seen that also $\bar{E}_{m}(x)$ is a spline function of degree $m$ having its knots at the integers. From the unicity of the solution of the problem (1.6) we conclude that

$$
\mathscr{E}_{m}(x)= \begin{cases}\bar{E}_{m}\left(x+\frac{1}{2}\right) / \bar{E}_{m}\left(\frac{1}{2}\right) & \text { if } m \text { is even }  \tag{1.10}\\ \bar{E}_{m}(x) / \bar{E}_{m}(0) & \text { if } m \text { is odd } .\end{cases}
$$

For the role of the Euler splines in Kolmogorov's solution of Landau's problem for the real axis see [6, Section 1].
C. The Bernoulli monosplines

We consider the

$$
\begin{equation*}
\operatorname{CIP}\left(\nu^{m} ; S_{m} \cap F^{*}\right) \tag{1.11}
\end{equation*}
$$

and observe that by Theorems 1 and 3 its unique solution is the spline function

$$
\begin{equation*}
S(x)=\sum_{-\infty}^{\infty} \nu^{n_{l}} L_{m}(x-v) \tag{1.12}
\end{equation*}
$$

Since $S(x)$ interpolates $x^{m}$ at the integers, if we define the remainder $R(x)$ by

$$
\begin{equation*}
x^{m}=S(x)+R(x) \tag{1.13}
\end{equation*}
$$

then

$$
\begin{equation*}
R(\nu)=0 \quad \text { for all } \nu \tag{1.14}
\end{equation*}
$$

We may restate our result as follows: First we recall that a function of the form

$$
\begin{equation*}
R(x)=x^{m}-S(x), \quad \text { where } \quad S(x) \in S_{m} \tag{1.15}
\end{equation*}
$$

is called a cardinal monospline of degree $m$. Besides (1.14) our monospline $R(x)$ also satisfies

$$
\begin{equation*}
R(x) \in F^{*} \tag{1.16}
\end{equation*}
$$

We also know, by Theorem 1 , that the monospline $R(x)$ is uniquely characterized, among monosplines, by the properties (1.14) and (1.16).

However, a monospline satisfying these conditions was known for a long time: Let $B_{m}(x)$ be the Bernoulli polynomial and let $\bar{B}_{m}(x)$ denote its periodic extension of period 1. It is known that $\bar{B}_{m}(0)=B_{m}$ for all $m \geqslant 2$ and that $\bar{B}_{m}\left(\frac{1}{2}\right)=0$ if $m$ is odd [2, Sections 2 and 3]. These remarks establish the following theorem.

Theorem 8. (1) The monospline

$$
\begin{equation*}
\bar{B}_{2 k}(x)-B_{2 k} \tag{1.17}
\end{equation*}
$$

is uniquely characterized among all monosplines of degree $2 k$ by the two requirements (1.14) and (1.16).
(2) The monospline

$$
\begin{equation*}
\bar{B}_{2 k+1}\left(x+\frac{1}{2}\right) \tag{1.18}
\end{equation*}
$$

is uniquely characterized among all monosplines of degree $2 k+1$ by the two requirements (1.14) and (1.16).

Finally, the following identities hold

$$
x^{m}=\sum_{-\infty}^{\infty} \nu^{m} L_{m}(x-\nu)+ \begin{cases}\bar{B}_{m}(x)-B_{m} & \text { if } m \text { is even },  \tag{1.19}\\ \bar{B}_{m}\left(x+\frac{1}{2}\right) & \text { if } m \text { is odd } .\end{cases}
$$

Alternatively, the Bernoullian functions can be defined as solutions of this problem, i.e., by cardinal spline interpolation of $x^{m}$, and all their properties developed starting from this definition.

An entirely different characterization of $\bar{B}_{m}(x)$ among monosplines was recently given in [5].

## 2. Proof of the Unicity in Theorem 1

Theorem 1 being obvious if $m=1$, we shall assume that $m \geqslant 2$.
Let

$$
\begin{equation*}
S_{m}^{0}=\left\{S(x) ; S(x) \in S_{m}, S(\nu)=0 \text { for all integers } v\right\} \tag{2.1}
\end{equation*}
$$

In [4, Section 9] we proved a Theorem 11 which asserts the following:
If $1 \leqslant p \leqslant \infty$ and if

$$
\begin{equation*}
S(x) \in S_{m}{ }^{0} \cap L_{p} \tag{2.2}
\end{equation*}
$$

then

$$
\begin{equation*}
S(x)=0 \text { for all } x \tag{2.3}
\end{equation*}
$$

The method used in [4] to establish this proposition will easily allow us to prove the following

Lemma 2. If

$$
\begin{equation*}
S(x) \in S_{m}^{0} \cap F^{*} \tag{2.4}
\end{equation*}
$$

then again (2.3) holds.
We see that the assumption (2.2) has been replaced by the new assumption (2.4).

Proof. In [4, relation (9.14)] it is shown that every element of $S_{m}{ }^{0}$ admits a unique representation

$$
S(x)=\sum_{v=1}^{2 s} a_{v} S_{v}(x), \quad \text { where } \quad 2 s= \begin{cases}m-2 & \text { if } m \text { is even }  \tag{2.5}\\ m-1 & \text { if } m \text { is odd }\end{cases}
$$

where the $S_{v}(x)$ are the so-called eigensplines of the class $S_{m}{ }^{0}$. The properties of these eigensplines; in particular, the relations (9.18) of [4], and the magnitudes of the corresponding eigenvalues $\lambda_{\nu}$, show easily that if the function (2.5) is in $F^{*}$, hence in some $F_{s}$, then all the coefficients $a_{\nu}$ must vanish, and therefore (2.3) holds.

Returning to the unicity in Theorem 1, let $S_{1}(x)$ and $S_{2}(x)$ be two solutions of the problem (13). It follows that

$$
S_{1}(x)-S_{2}(x) \in S_{m}^{0} \quad \text { and } \quad S_{1}(x)-S_{2}(x) \in F^{*}
$$

and therefore

$$
S_{1}(x)=S_{2}(x) \text { for all } x
$$

by Lemma 2.

## 3. The Fundamental Function $L_{m}(x)$

Since Theorem 1, beyond unicity, is not yet available at this point, the function $L_{m}(x)$ will now be constructed directly, as already done [3]. It was shown in [4, formula (2.2) and Lemma 6] that the real cosine polynomial

$$
\begin{equation*}
\phi_{m}(u)=\sum_{|\nu| \leqslant m / 2} M_{m}(\nu) e^{i \nu u} \tag{3.1}
\end{equation*}
$$

is positive for all real $u$. Also that its reciprocal has a Fourier series expansion

$$
\begin{equation*}
\frac{1}{\phi_{m}(u)}=\sum_{\nu} \omega_{\nu}^{(m)} e^{i \nu u} \tag{3.2}
\end{equation*}
$$

with the following property: The series $\sum_{v} \omega_{v}^{(m)} z^{\nu}$ is the Laurent expansion on $|z|=1$ of a rational function having no poles on the circle $|z|=1$ [4, p. 182]. This implies the existence of an inequality of the form

$$
\begin{equation*}
\left|\omega_{\nu}^{(m)}\right| \leqslant C e^{-\gamma|\nu|}, \quad \text { for all } \nu \tag{3.3}
\end{equation*}
$$

for appropriate positive $C$ and $\gamma$ depending on $m$.
We now define the spline function

$$
\begin{equation*}
L_{m}(x)=\sum_{\nu} \omega_{\nu}^{(m)} M_{m}(x-\nu) \tag{3.4}
\end{equation*}
$$

From the mutually reciprocal Fourier expansions (3.1) and (3.2), we obtain by multiplication the relations

$$
\sum_{\nu} \omega_{\nu}^{(m)} M_{m}(j-\nu)=\delta_{j}= \begin{cases}1 & \text { if } j=0  \tag{3.5}\\ 0 & \text { if } j \neq 0\end{cases}
$$

In terms of (3.4), (3.5) may be written as

$$
\begin{equation*}
L_{m}(j)=\delta_{j} \tag{3.6}
\end{equation*}
$$

and we conclude that the function (3.4) has the desired property (16).

## 4. Proof of Theorem 2

Using (3.3), the inequalities $0 \leqslant M_{n}(x) \leqslant M_{m}(0)$, and that $M_{m}(x)=0$ if $|x| \geqslant m / 2$, we find from (3.4) that

$$
\begin{aligned}
\left|L_{m}(x)\right| & \leqslant \sum_{\nu>x-m / 2}\left|\omega_{\nu}^{(m)}\right| M_{m}(x-\nu) \\
& \leqslant M(0) \sum_{\nu>x-m / 2}\left|\omega_{v}^{(m)}\right|<M_{m}(0) C \sum_{v>x-m / 2} e^{-\gamma v}
\end{aligned}
$$

If $x \geqslant m / 2$ we easily conclude that

$$
\left|L_{m}(x)\right|<c_{1} e^{-\gamma x}
$$

where $c_{1}=M_{m}(0) C\left(1-e^{-\nu}\right)^{-1} e^{m \gamma / 2}$. The function $L_{m}(x)$ being even, this implies (17) with $\gamma_{m}=\gamma$. That $L_{m}(x)$ is uniquely defined by the properties (16) and (17) we already know from the already established unicity in Theorem 1.

## 5. Proof of Theorem 3 and the Proof of Theorem 1 Completed

Both these proofs are simultaneously carried out by showing that

$$
\begin{equation*}
S(x)=\sum_{\nu} y_{\nu} L_{m}(x-\nu) \tag{5.1}
\end{equation*}
$$

converges locally uniformly and furnishes a solution of the problem (13). By our assumption (14) we may write $\left|y_{v}\right|<A\left(|\nu|^{s}+1\right)$ for all $\nu$, and Theorem 2 shows that the series (5.1) is termwise dominated by the series

$$
\begin{equation*}
\sum_{v} A C_{m}\left(|\nu|^{s}+1\right) e^{-\nu|x-\nu|} \tag{5.2}
\end{equation*}
$$

which evidently converges uniformly in $x$ in every finite interval $|x| \leqslant K$. Therefore (5.1) converges locally uniformly and defines an element of $S_{m}$ satisfying the relation $S(\nu)=y_{v}$, for all $\nu$, in view of (16).

There remains to show that $S(x) \in F_{s}$ or

$$
\begin{equation*}
\sum_{v} y_{v} L_{m}(x-\nu)=O\left(|x|^{s}\right) \quad \text { as } \quad x \rightarrow \pm \infty \tag{5.3}
\end{equation*}
$$

By (5.2) we see that it suffices to show that

$$
\begin{equation*}
\sum_{\nu}|\nu|^{s} e^{-\gamma|x-\nu|}=O\left(|x|^{s}\right) \quad \text { as } \quad x \rightarrow \pm \infty \tag{5.4}
\end{equation*}
$$

and by symmetry we may establish this statement only if $x \rightarrow+\infty$. As the sum of the series (5.4) for negative values of $\nu$ is clearly $=0(1)$, it is enough to show that

$$
\begin{equation*}
\sum_{\nu=1}^{\infty} \nu^{s} e^{-\gamma|x-v|}=O\left(x^{s}\right) \quad \text { as } \quad x \rightarrow+\infty \tag{5.5}
\end{equation*}
$$

We have

$$
\begin{align*}
\sum_{v=1}^{\infty}\left(\frac{\nu}{x}\right)^{s} e^{-\nu|x-\nu|} & =\sum_{v \leqslant x+1}+\sum_{\nu>x+1} \\
& <\sum_{v \leqslant x+1} e^{-\nu(x-\nu)}+\sum_{v>x+1} \nu^{s} x^{-s} e^{-\gamma|x-\nu|} \\
& =O(1)+x^{-s} \sum_{v>x+1} \nu^{s} e^{-\gamma(\nu-x)} \\
& =O(1)+x^{-s} e^{\gamma s} \sum_{v>x+1} \nu^{s} e^{-\gamma v} \tag{5.6}
\end{align*}
$$

If we restrict $x$ to a range $x>\xi$ in which the function $x^{s} e^{-v x}$ is decreasing and convex, then we may replace the last sum by an integral and obtain

$$
\begin{aligned}
& x^{-s} e^{\gamma x} \sum_{\nu>x+\mathbf{1}} \nu^{s} e^{-\gamma r}<x^{-s} e^{\nu x} \int_{x}^{\infty} t^{s} e^{-\gamma t} d t \\
& \quad=\int_{x}^{\infty}(t / x)^{s} e^{-\gamma(t-x)} d t=\int_{0}^{\infty}\left(1+\frac{u}{x}\right)^{s} e^{-\gamma u} d u
\end{aligned}
$$

by the change of variables $t=x+u$. The last integral being $O(1)$ as $x \rightarrow+\infty$, we see by (5.6) that (5.5) holds.

## 6. Proof of Theorem 5

We need a result from [3] concerning the so-called method of central interpolation which is as follows. Let $\left(y_{v}\right)$ be a sequence of data. We select
$m$ consecutive ordinates, say $y_{r}, y_{r+1}, \ldots, y_{r+m-1}$, and construct the Lagrange polynomial $P_{r}(x)$, of degree $m-1$, that interpolates them and define the interpolating function $F(x)$ by the relation

$$
F(x)=P_{r}(x)
$$

within the interval ( $\alpha_{r}, \beta_{r}$ ), of length unity, whose midpoint coincides with the midpoint of the interval ( $r, r+m-1$ ). Varying $r$ over all integers we see that $F(x)$ is defined by a piecewise polynomial function. Applying this method to the "unit" sequence $y_{v}=\delta_{v}$, defined by (15), we obtain an interpolating function that we denote by $C_{m}(x)$. It is readily seen $[3, \mathrm{p} .57$, where the graphs of $C_{m}(x)$, for $m=1,2,3,4$, are also to be found] that the interpolant for an arbitrary sequence ( $y_{v}$ ) is given by the formula

$$
F(x)=\sum_{-\infty}^{\infty} y_{\nu} C_{m}(x-\nu) .
$$

Evidently, from the definition of $C_{m}(x)$ as the interpolant of $\left(\delta_{\nu}\right)$, we find that

$$
\begin{equation*}
C_{m}(\nu)=\delta_{\nu} \text { for all } \nu \tag{6.1}
\end{equation*}
$$

We shall need
Lemma 3. In terms of the $B$-splines $M_{m}(x)$ and the coefficients of the expansion (27) we have the identity

$$
\begin{equation*}
C_{m}(x)=\sum_{r=0}^{s}(-1)^{r} \gamma_{2 r}^{(m)} M_{m}^{(2 r)}(x), \quad \text { where } \quad s=\left[\frac{m-1}{2}\right] . \tag{6.2}
\end{equation*}
$$

For proof, see [3, Part B, Section 2.3].
Remark. Observe that if $m$ is odd then functions with discontinuities of the first kind appear on both sides of (6.2). The identity (6.2) holds for all real $x$ if we normalize discontinuous functions like $C_{2 k+1}(x)$ and $M_{m}^{(m-1)}(x)$ by requiring that

$$
f(x)=\frac{1}{2}(f(x+0)+f(x-0)) \text { for all } x .
$$

In order to establish the relation (28) we start from (24) or

$$
\begin{equation*}
S(x)=\sum_{v} c_{\nu} M_{m}(x-\nu) \tag{6.3}
\end{equation*}
$$

and obtain by differentiations for integer $x=n$

$$
\begin{equation*}
S^{(2 r)}(n)=\sum_{\nu} c_{\nu} M_{m}^{(2 r)}(n-\nu) \quad(r=0,1, \ldots, s), \tag{6.4}
\end{equation*}
$$

where $s=[(m-1) / 2]$. Multiplying both sides by $(-1)^{r} \gamma_{2 r}^{(m)}$ and summing over $r$ we get

$$
\begin{aligned}
\sum_{r=0}^{s}(-1)^{r} \gamma_{2 r}^{(m)} S^{(2 r)}(n) & =\sum_{r=0}^{s}(-1)^{r} \gamma_{2 r}^{(m)} \sum_{\nu} c_{\nu} M_{m}^{(2 r)}(n-\nu) \\
& =\sum_{\nu} c_{\nu} \sum_{r=0}^{s}(-1)^{r} \gamma_{2 r}^{(m)} M_{m}^{(2 r)}(n-\nu) \\
& =\sum_{\nu} c_{\nu} C_{m}(n-\nu)=c_{n}
\end{aligned}
$$

in view of the relations (6.2) and (6.1). This completes a proof of Theorem 5.

## 7. Proof of Theorem 4

For the simple proof of the sufficiency of the condition (26) see [4, pp. 199200]. Let us now assume that

$$
\begin{equation*}
S(x) \in L_{p} \tag{7.1}
\end{equation*}
$$

and show that the $c_{\nu}$ in (6.3) satisfy

$$
\begin{equation*}
\left(c_{v}\right) \in l_{p} \tag{7.2}
\end{equation*}
$$

Let $R(x)$ be a polynomial of degree $k$ in the interval [ 0,1 ]. By Markov's theorem we obtain the string of inequalities

$$
\begin{aligned}
& \max \left|R^{\prime}\right| \leqslant 2 k^{2} \max |R| \\
& \max \left|R^{n}\right| \leqslant 2(k-1)^{2} \max \left|R^{\prime}\right| \\
& \vdots \\
& \max \left|R^{(r)}\right| \leqslant 2(k-r+1)^{2} \max \left|R^{(r-1)}\right|, \quad(r \leqslant k),
\end{aligned}
$$

and multiplying them together we obtain

$$
\begin{equation*}
\max \left|R^{(r)}\right| \leqslant A(k, r) \max |R| \quad(r=1, \ldots, k) \tag{7.3}
\end{equation*}
$$

where $A(k, r)=2^{r}(k(k-1) \cdots(k-r+1))^{2}$.
Let $p=\infty$ in (7.1), which means that $S(x)$ is bounded. Applying (7.3), with $k=m-1$, to each of the polynomial components of $S(x)$ in each of the successive interval $[\nu, \nu+1]$, we conclude that the $m$ sequences

$$
\left(S^{(r)}(\nu)\right),(r=0,1, \ldots, m-1)
$$

are bounded. Since in (28) $2 s \leqslant m-1$ we conclude from (28) that the sequence $\left(c_{\nu}\right)$ is also bounded so that (7.2) holds.

Let now $1 \leqslant p<\infty$. Assuming $P(x) \in \pi_{m-1}$ and setting

$$
R(x)=\int_{0}^{x} P(t) d t \quad \text { in } \quad 0 \leqslant x \leqslant 1
$$

we apply (7.3) to this polynomial of degree $k=m$ and obtain for $r \leqslant m-1$

$$
\begin{aligned}
\max \left|P^{(r)}\right| & =\max \left|R^{(r+1)}\right| \leqslant A(m, r+1) \cdot \max |R| \\
& =A \cdot \max \left|\int_{0}^{x} P(t) d t\right| \leqslant A \cdot \int_{0}^{1}|P(t)| d t
\end{aligned}
$$

Hence

$$
\max \left|P^{(r)}\right| \leqslant A \cdot\left(\int_{0}^{1}|P(t)|^{p} d t\right)^{1 / p}
$$

by Hölder's inequality. Therefore,

$$
\begin{equation*}
\max \left|P^{(r)}\right|^{p} \leqslant A^{p} \cdot \int_{0}^{1}|P(t)|^{p} d t \quad(r=0, \ldots, m-1) \tag{7.4}
\end{equation*}
$$

Assume for the moment that $m$ is even and observe that in (28) $2 s=m-2$. Applying (7.4) to the components of $S(x)$ in successive intervals $[\nu, v+1]$ and summing the results, we obtain

$$
\begin{array}{r}
\left(\left\|S^{(r)}(\nu)\right\|_{p}\right)^{p} \leqslant \sum_{\nu} \max _{[v, \nu+1]}\left|S^{(r)}(x)\right|^{p} \leqslant A^{p} \cdot \int_{-\infty}^{\infty}|S(t)|^{p} d t<\infty \\
(r=0,1, \ldots, m-2)
\end{array}
$$

and this shows that the $s+1$ sequences appearing on the right side of (28) are all in $l_{p}$. It follows that $\left(c_{v}\right) \in l_{p}$.

If $m$ is odd, then in (28) $2 s=m-1$. Applying (7.4) to the components of $S(x)$ in the intervals [ $\nu-\frac{1}{2}, \nu+\frac{1}{2}$ ] we obtain similarly that

$$
\begin{array}{r}
\left(\left\|S^{(r)}(\nu)\right\|_{\mathfrak{p}}\right)^{p} \leqslant \sum_{\nu} \max _{\left[\nu-\frac{1}{2}, v+\frac{1}{2}\right]}\left|S^{(r)}(x)\right|^{p}<A^{p} \int_{-\infty}^{\infty}|S(t)|^{p} d t<\infty \\
(r=0,1, \ldots, m-1)
\end{array}
$$

and (26) is thereby similarly established.

Added in proof: Theorem 1 for the case when $m$ is even and $s=0$ was first established by Ju. N. Subbotin in 1965 in the paper quoted among the references of [4] above.

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